
CS-C3100 Computer Graphics

4.1 Tensor Product
Spline Surfaces

Representing Surfaces

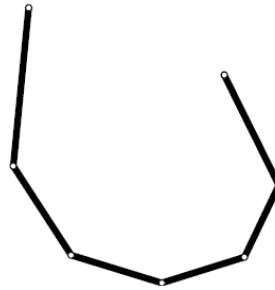
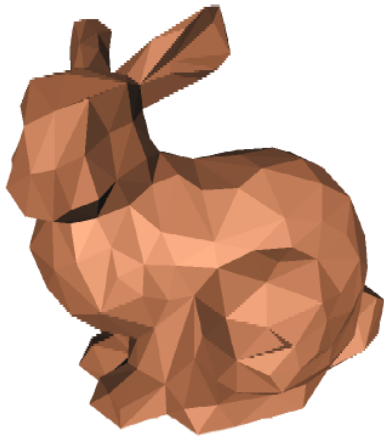
- Triangle meshes ✓
 - Surface analogue of polylines, this is what GPUs draw
- **Tensor Product Splines (this video)**
 - **Surface analogue of spline curves**
- Subdivision surfaces (next video)
- Implicit surfaces
 - $f(x,y,z)=0$
- Procedural
 - e.g. surfaces of revolution, generalized cylinder
- From volume data (medical images, etc.)

In This Video

- Tensor product spline patches
 - Bézier and B-spline
- Tangents and normals from partial derivatives
- Displacement mapping
- *Extra: matrix & tensor notation for spline patches*
 - Slides only

Triangle Meshes

- What you've used so far in Asst 1
- Triangle represented by 3 vertices
- **Pro:** simple, can be rendered directly
- **Cons:** not smooth, needs many triangles to approximate smooth surfaces (tessellation)



Smooth Surfaces?

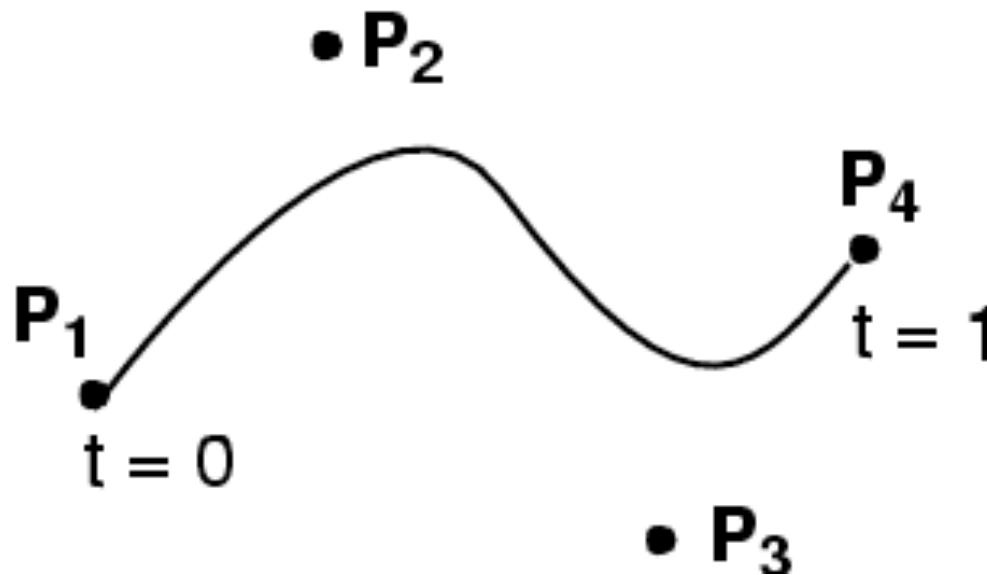
- $\mathbf{P}(t) =$

$(1-t)^3$	\mathbf{P}_1	
$+$	$3t(1-t)^2$	\mathbf{P}_2
$+$	$3t^2(1-t)$	\mathbf{P}_3
$+$	t^3	\mathbf{P}_4

What's the dimensionality of a curve? 1D!

Why? Just one scalar parameter, t

What about a surface?



Smooth Surfaces?

- $\mathbf{P}(t) =$

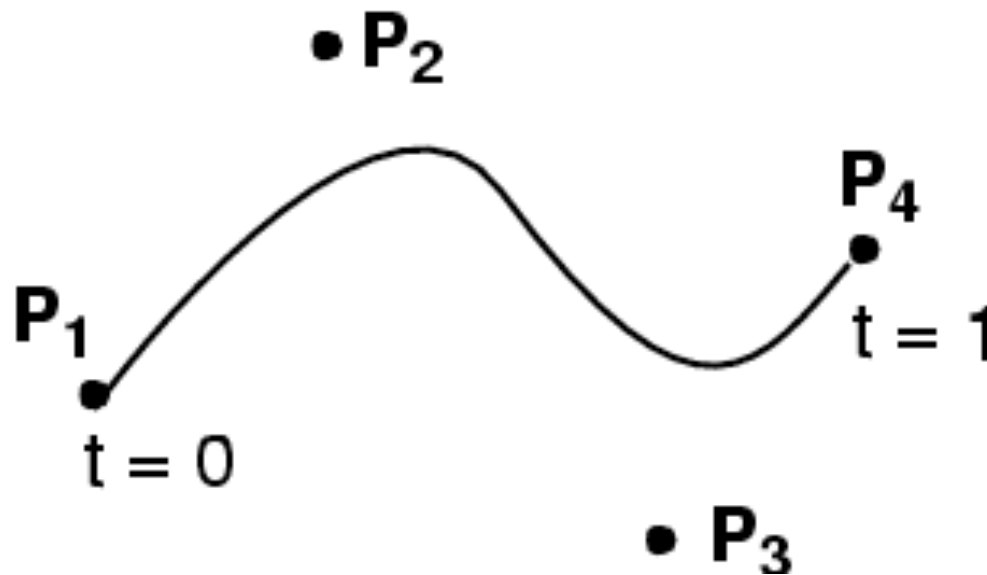
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What's the dimensionality of a curve? 1D!

Why? Just one scalar parameter, t

What about a surface?

2D!

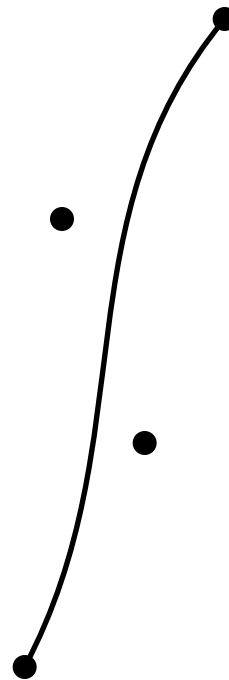


How to Build Them?

- $\mathbf{P}(u) =$

$(1-u)^3$	\mathbf{P}_1
$+$	\mathbf{P}_2
$3u(1-u)^2$	
$+$	\mathbf{P}_3
$3u^2(1-u)$	
$+$	\mathbf{P}_4
u^3	

(Note! We relabeled t to u)

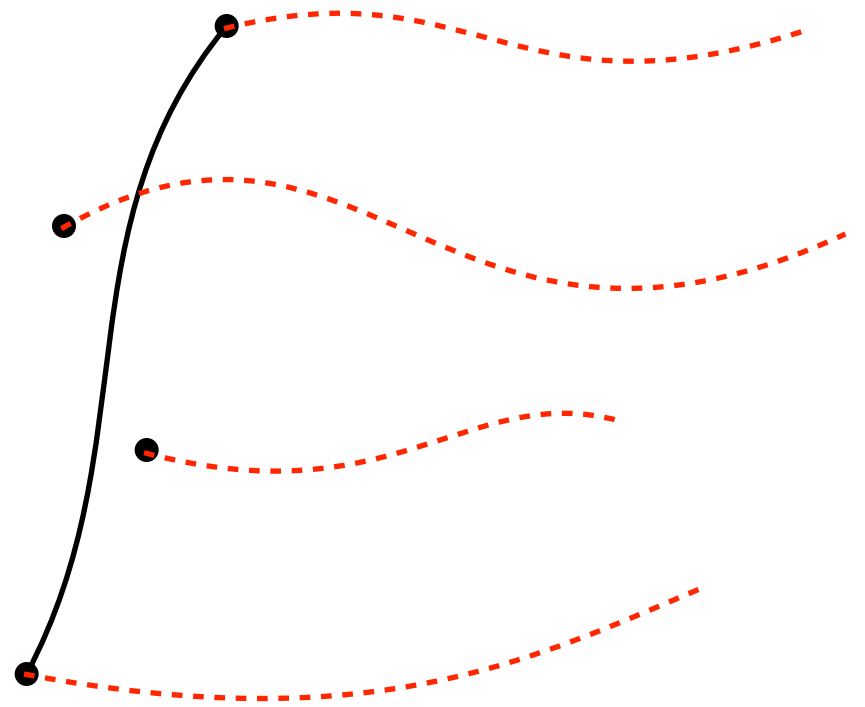


How to Build Them? Here's an Idea

- $\mathbf{P}(u) =$

$(1-u)^3$	\mathbf{P}_1
$+ 3u(1-u)^2$	\mathbf{P}_2
$+ 3u^2(1-u)$	\mathbf{P}_3
$+ u^3$	\mathbf{P}_4

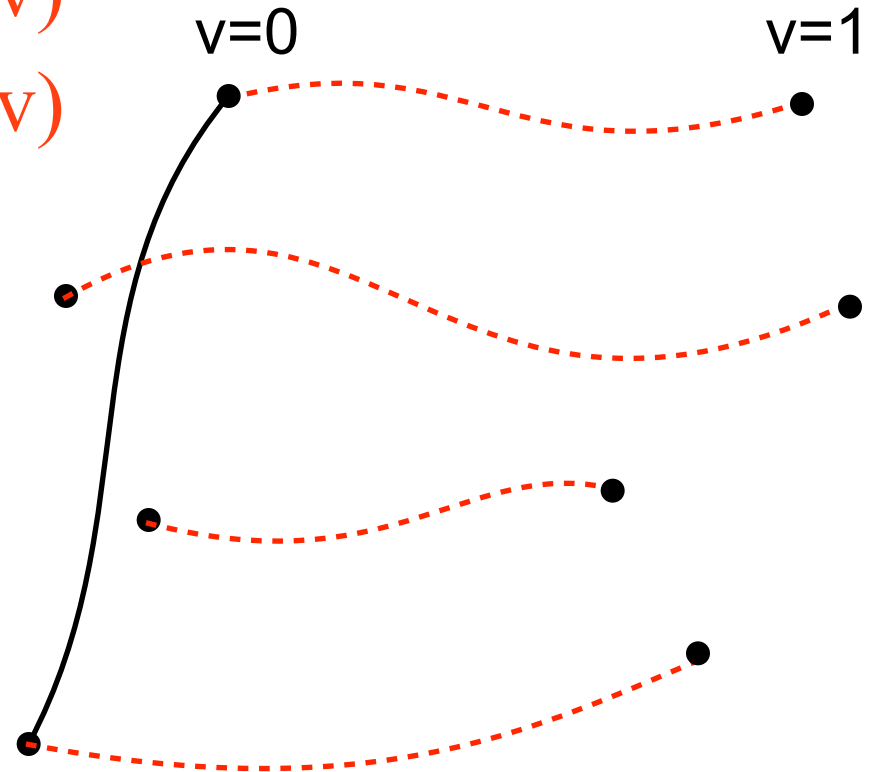
(Note! We relabeled t to u)



Here's an Idea

- $\mathbf{P}(u, \mathbf{v}) = (1-u)^3 \quad \mathbf{P}_1(\mathbf{v})$
+ $3u(1-u)^2 \quad \mathbf{P}_2(\mathbf{v})$
+ $3u^2(1-u) \quad \mathbf{P}_3(\mathbf{v})$
+ $u^3 \quad \mathbf{P}_4(\mathbf{v})$

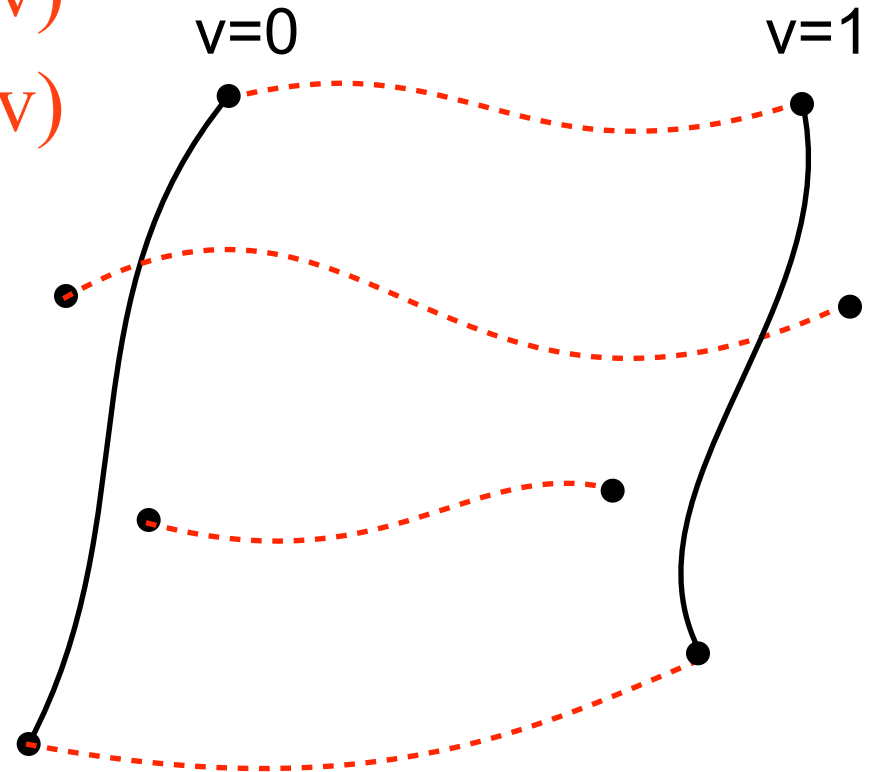
- Let's make
the \mathbf{P}_i s move along
curves!



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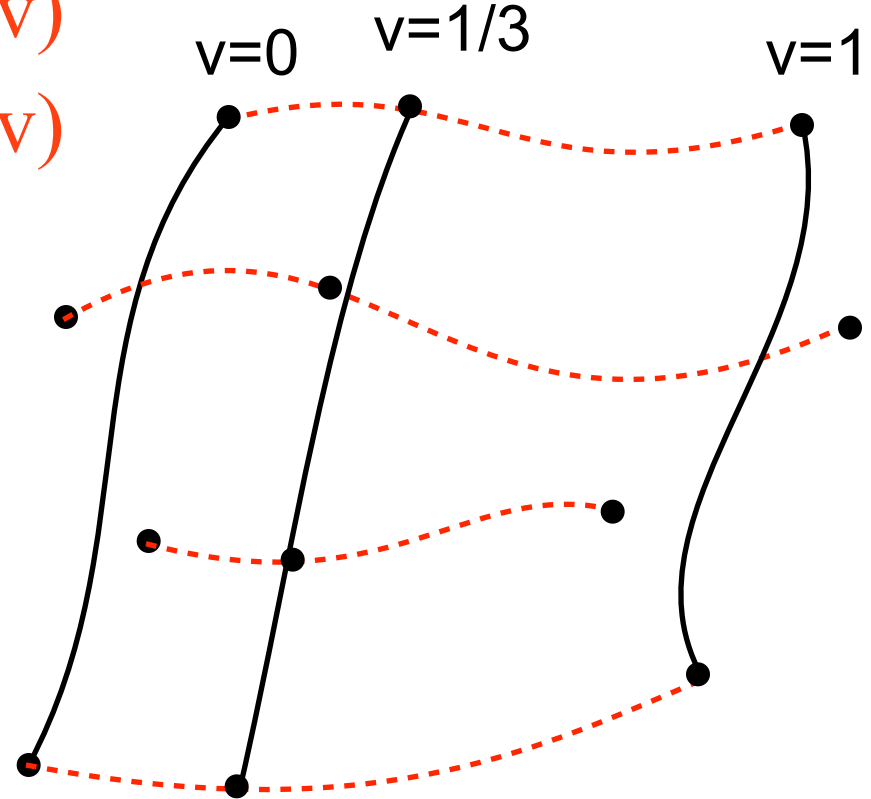
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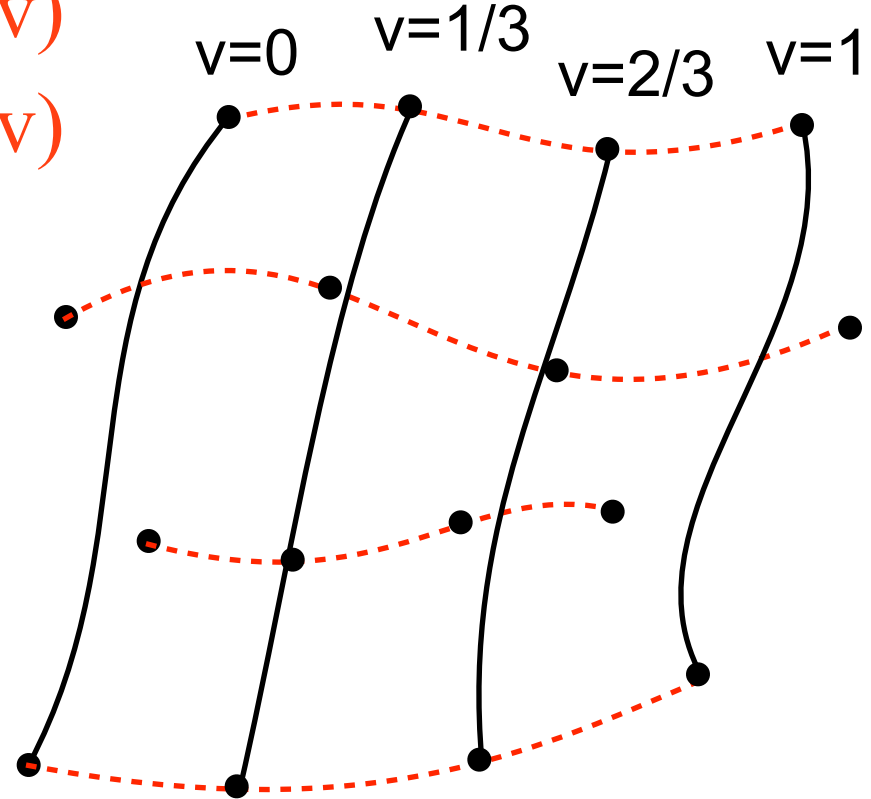
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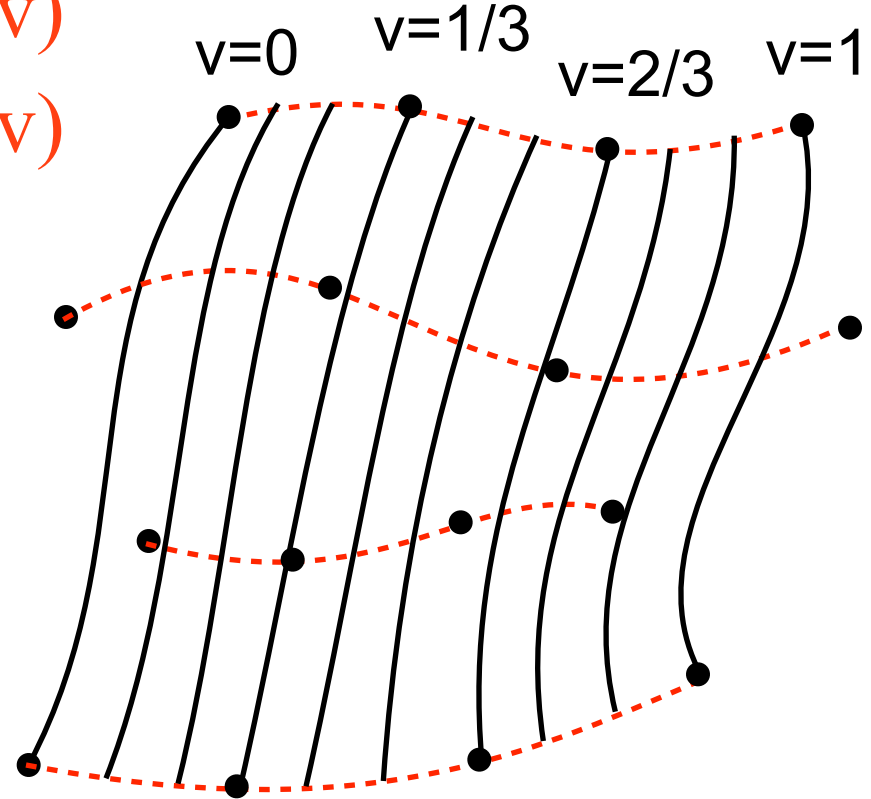
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- Let's make the \mathbf{P}_i s move along curves!

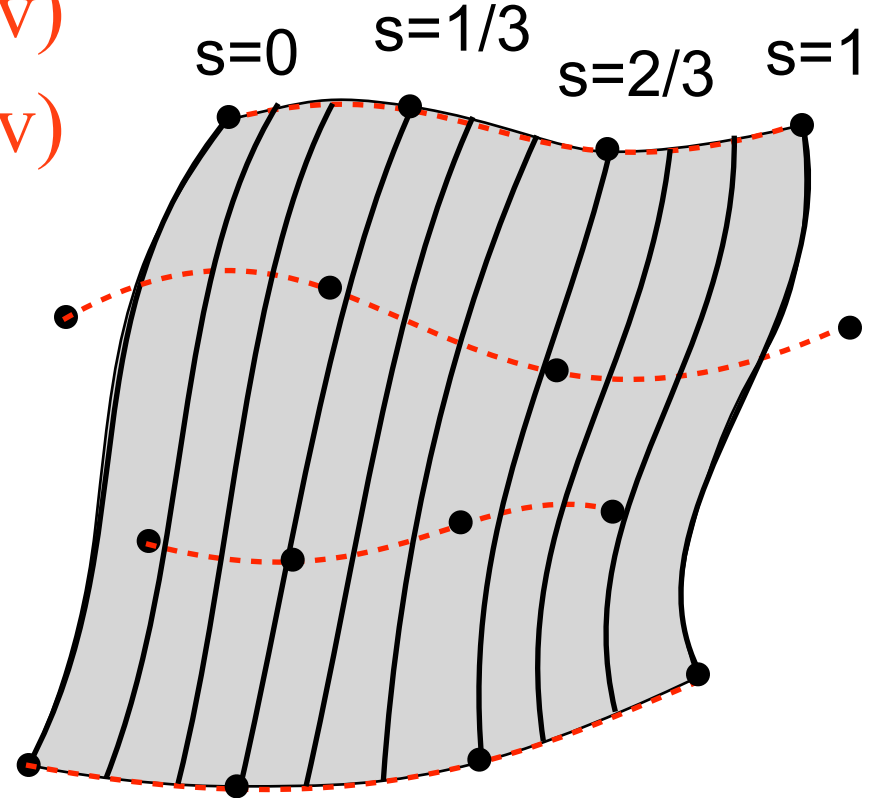


Here's an Idea

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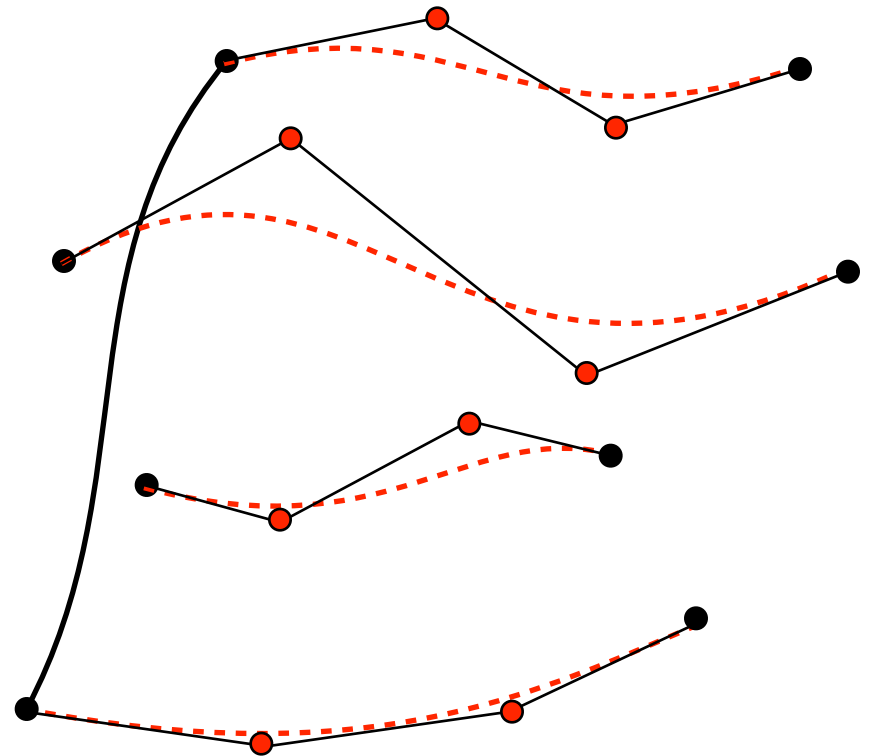
- Let's make the \mathbf{P}_i s move along curves!

A 2D surface patch!



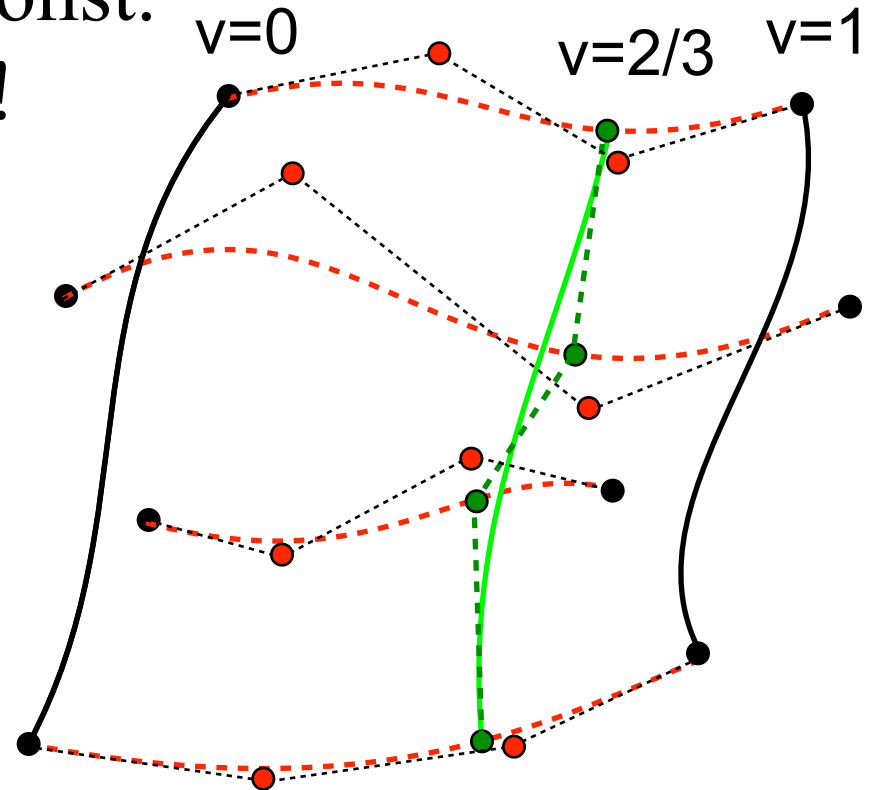
“Tensor Product Bézier Patches”

- In the previous, $\mathbf{P}_i(\mathbf{v})$ were just some curves
- What if we make **them** Bézier curves too?



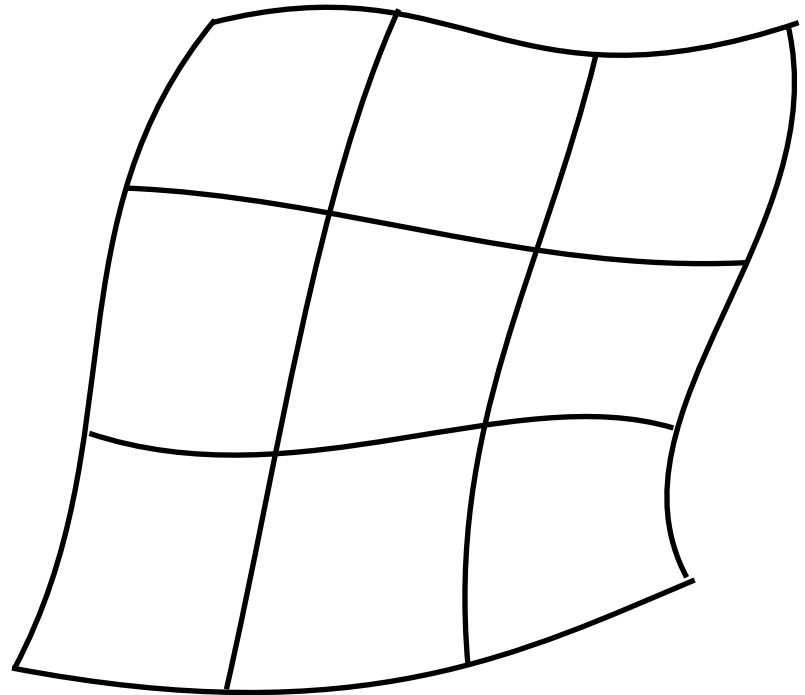
Tensor Product Bézier Patches

- In the previous, $\mathbf{P}_i(v)$ were just some curves
- What if we make **them** Bézier curves too?
- Each $u=\text{const.}$ **and** $v=\text{const.}$ curve is a Bézier curve!
- Note that the boundary control points (except corners) are NOT interpolated!



Tensor Product Bézier Patches

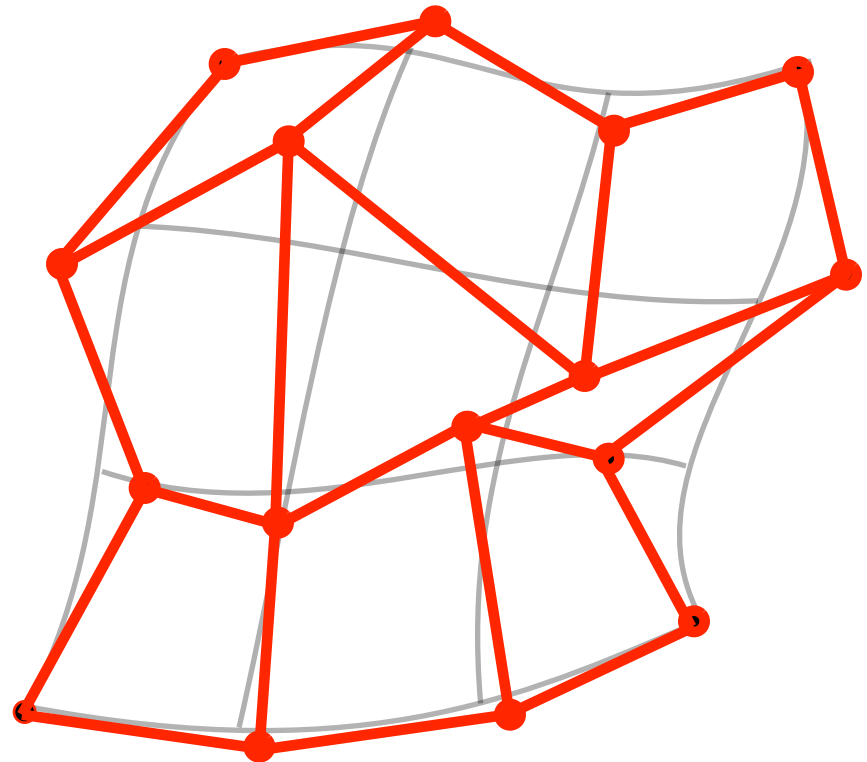
**A bicubic Bézier
surface**



Tensor Product Bézier Patches

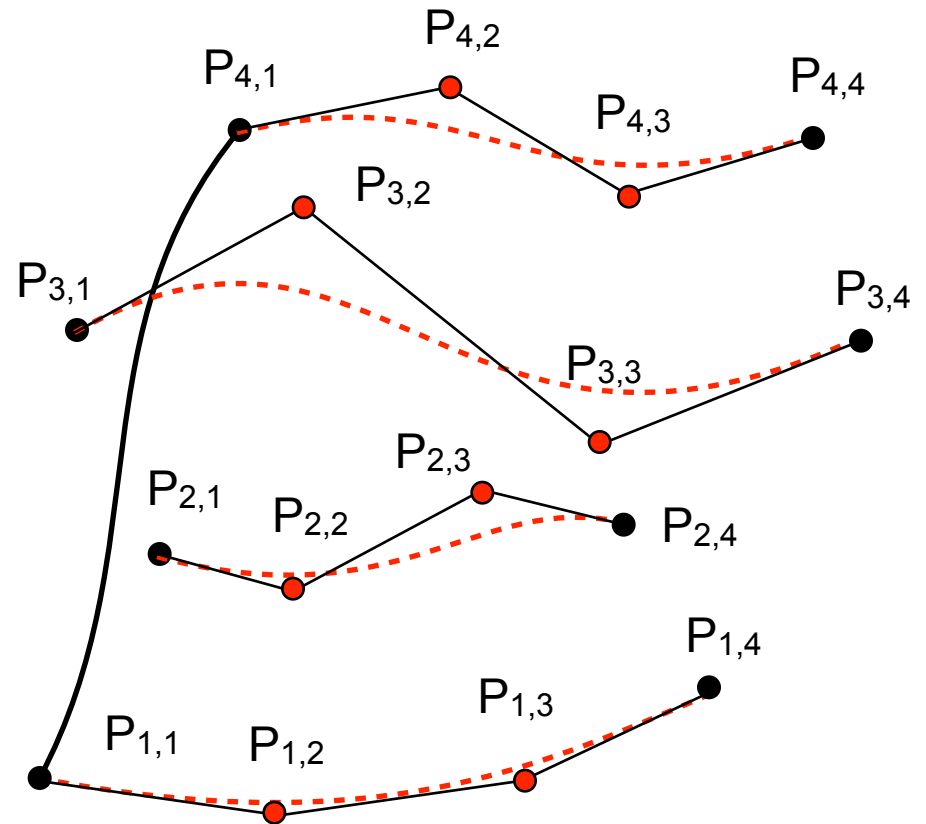
- Note that only the 4 corners are interpolated!

The “Control Mesh”
16 control points



Bicubics, Tensor Product

- $P(u,v) = B_1(u) * P_1(v)$
+ $B_2(u) * P_2(v)$
+ $B_3(u) * P_3(v)$
+ $B_4(u) * P_4(v)$
- $P_i(v) = B_1(v) * P_{i,1}$
+ $B_2(v) * P_{i,2}$
+ $B_3(v) * P_{i,3}$
+ $B_4(v) * P_{i,4}$



Bicubics, Tensor Product

- $P(u,v) = B_1(u) * P_1(v)$
+ $B_2(u) * P_2(v)$
+ $B_3(u) * P_3(v)$
+ $B_4(u) * P_4(v)$
- $P_i(v) = B_1(v) * P_{i,1}$
+ $B_2(v) * P_{i,2}$
+ $B_3(v) * P_{i,3}$
+ $B_4(v) * P_{i,4}$

$$P(u, v) = \sum_{i=1}^4 B_i(u) \left[\sum_{j=1}^4 P_{i,j} B_j(v) \right]$$
$$= \sum_{i=1}^4 \sum_{j=1}^4 P_{i,j} B_{i,j}(u, v)$$

with

$$B_{i,j}(u, v) = B_i(u) B_j(v)$$

Bicubics, Tensor Product

- $P(u, v) = B_1(u) * P_1(v)$
+ $B_2(u) * P_2(v)$
+ $B_3(u) * P_3(v)$
+ $B_4(u) * P_4(v)$
- $P_i(v) = B_1(v) * P_{i,1}$
+ $B_2(v) * P_{i,2}$
+ $B_3(v) * P_{i,3}$
+ $B_4(v) * P_{i,4}$

$$P(u, v) = \sum_{i=1}^4 B_i(u) \left[\sum_{j=1}^4 P_{i,j} B_j(v) \right]$$

*i*th control point for the u curve

$$= \sum_{i=1}^4 \sum_{j=1}^4 P_{i,j} B_{i,j}(u, v)$$

with Tensor product of B_i and B_j

$$B_{i,j}(u, v) = B_i(u) B_j(v)$$

Bicubics, Tensor Product

- $P(u,v) = B_1(u) * P_1(v)$
+ $B_2(u) * P_2(v)$
+ $B_3(u) * P_3(v)$
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- $P_i(v) = B_1(v) * P_{i,1}$
+ $B_2(v) * P_{i,2}$
+ $B_3(v) * P_{i,3}$
+ $B_4(v) * P_{i,4}$

$$P(u, v) =$$

$$\sum_{i=1}^4 \left[\sum_{j=1}^4 \right]$$

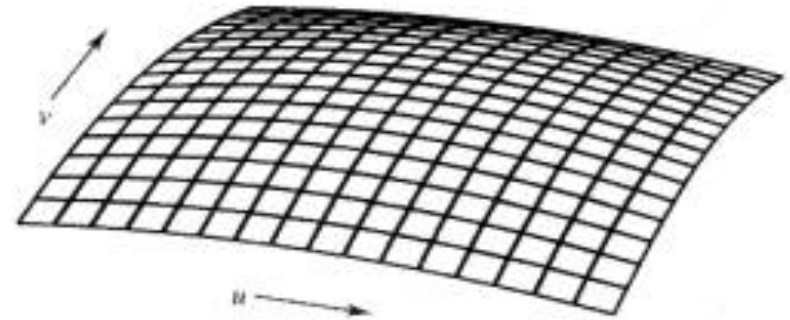
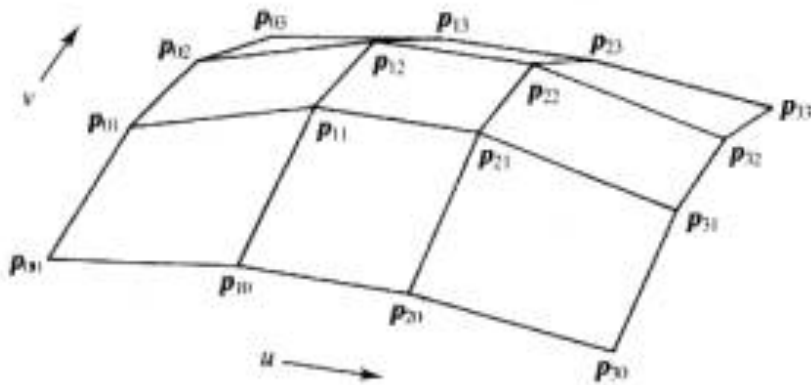
16 control points $P_{i,j}$
16 2D basis functions $B_{i,j}$

$$= \sum_{i=1}^4 \sum_{j=1}^4 P_{i,j} B_{i,j}(u, v)$$

$$B_{i,j}(u, v) = B_i(u) B_j(v)$$

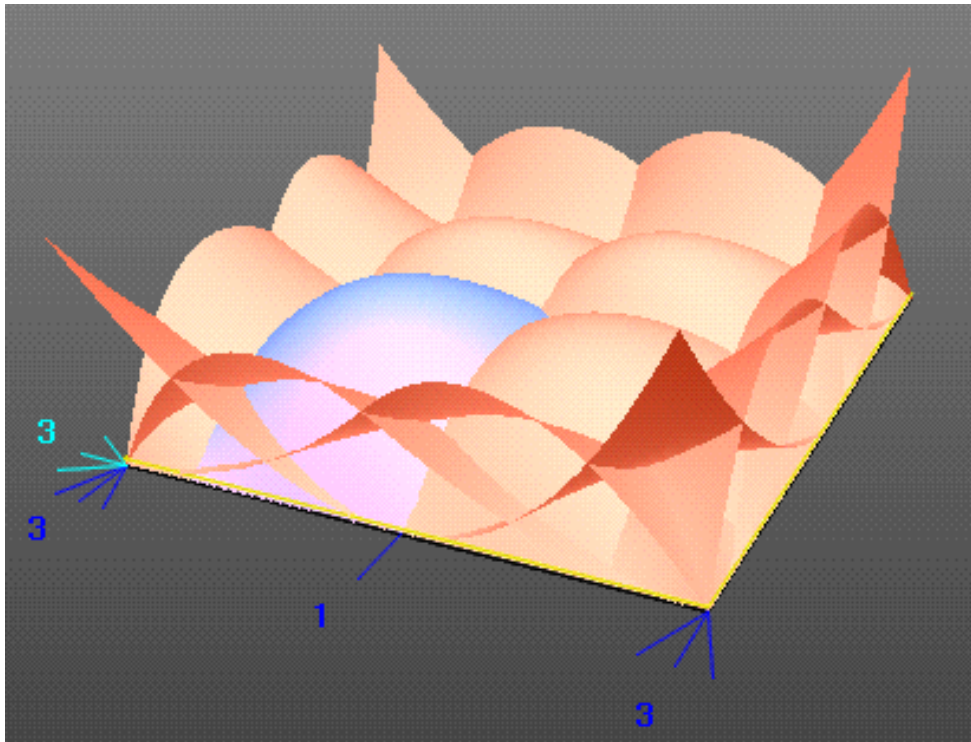
Recap: Tensor Bézier Patches

- Parametric surface $P(u,v)$ is a cubic polynomial of two variables u & v
- Defined by $4 \times 4 = 16$ control points $P_{1,1}, P_{1,2}, \dots, P_{4,4}$
- Interpolates 4 corners, approximates others



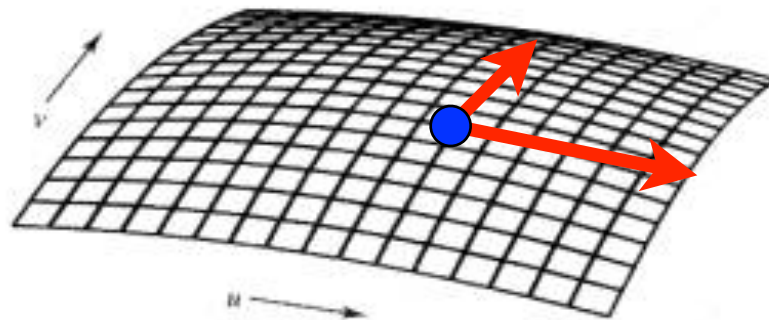
Tensor Product Bézier Patches

- Defined by $4 \times 4 = 16$ control points $P_{1,1}, P_{1,2}, \dots, P_{4,4}$
- Basis functions = products of two 1D Bernsteins:
 $B_1(u)B_1(v); B_1(u)B_2(v); \dots B_4(u)B_4(v)$



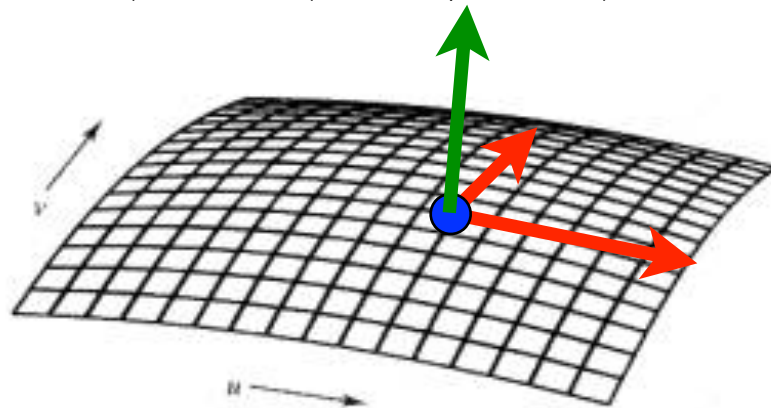
Tangents and Normals for Patches

- $P(u,v)$ is a **3D point** specified by u, v
- The **partial derivatives** $\partial P/\partial u$ and $\partial P/\partial v$ are 3D vectors
 - Both are tangent to surface at P



Tangents and Normals for Patches

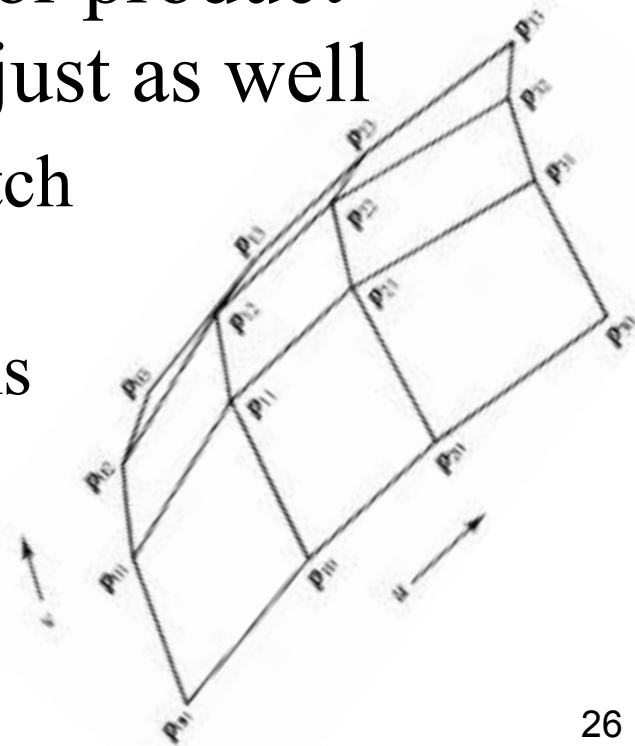
- $P(u,v)$ is a **3D point** specified by u, v
- The **partial derivatives** $\partial P/\partial u$ and $\partial P/\partial v$ are 3D vectors
 - Both are tangent to surface at P
 - **Normal** is perpendicular to both, i.e.,
$$n = (\partial P/\partial u) \times (\partial P/\partial v)$$



n is usually not unit, so must normalize!

Tensor Product B-Spline Patches

- Bézier and B-Spline curves are both cubics
 - \Rightarrow Can change between representations using matrices
- Consequently, you can build tensor product surface patches out of B-Splines just as well
 - Still 4×4 control points for each patch
 - 2D basis functions are pairwise products of B-Spline basis functions
 - Sliding window of 4×4 points
 - Yes, simple!

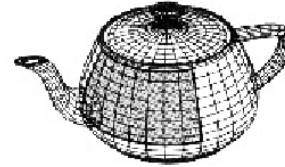


Tensor Product Spline Patches

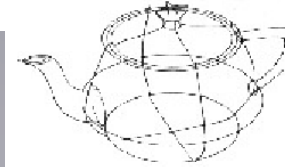
- Pros
 - Smooth
 - Defined by reasonably small set of points
- Cons
 - Harder to render (usually converted to triangles)
 - **Tricky to ensure continuity at patch boundaries**
- Extensions
 - Rational splines: Splines in homogeneous coordinates
 - NURBS: Non-Uniform Rational B-Splines
 - Like curves: ratio of polynomials, non-uniform location of control points, etc.

Utah Teapot: Tensor Bézier Splines

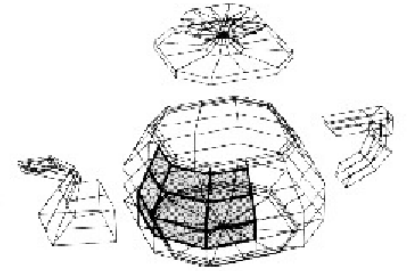
- Designed by Martin Newell



single shaded patch



Patch edges

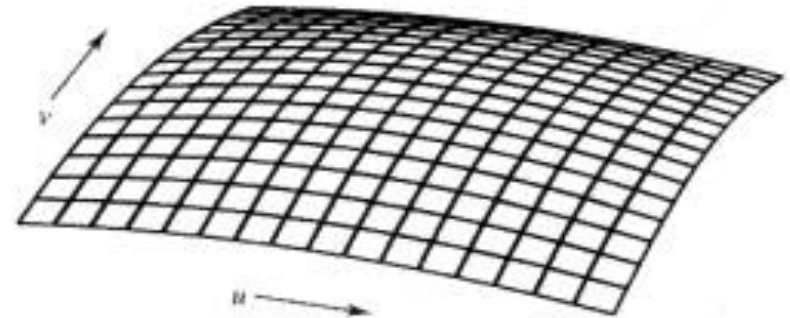
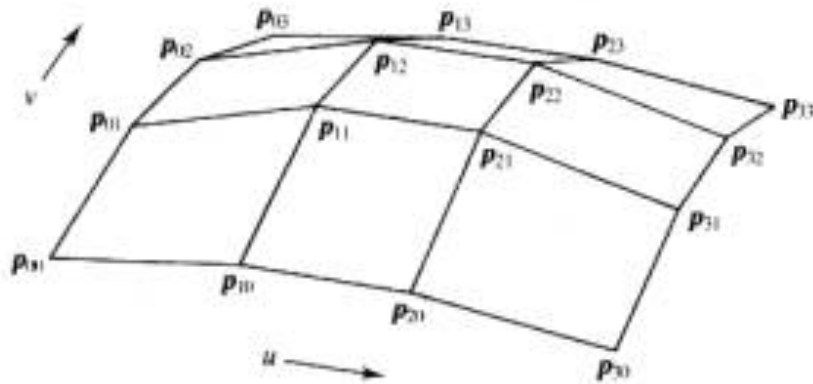


wireframe of the control points



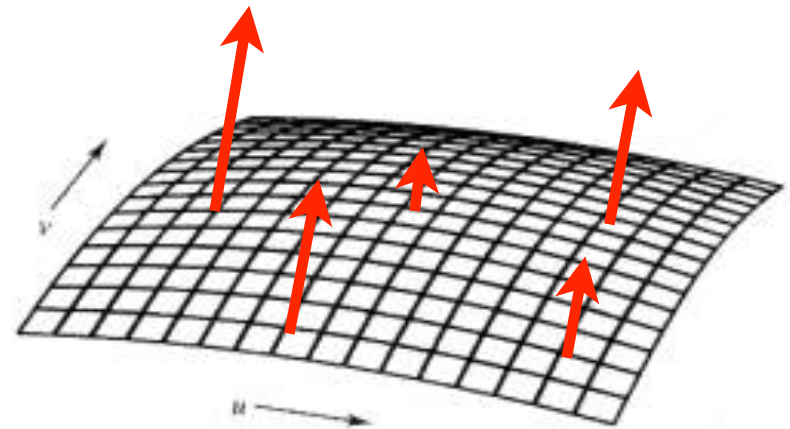
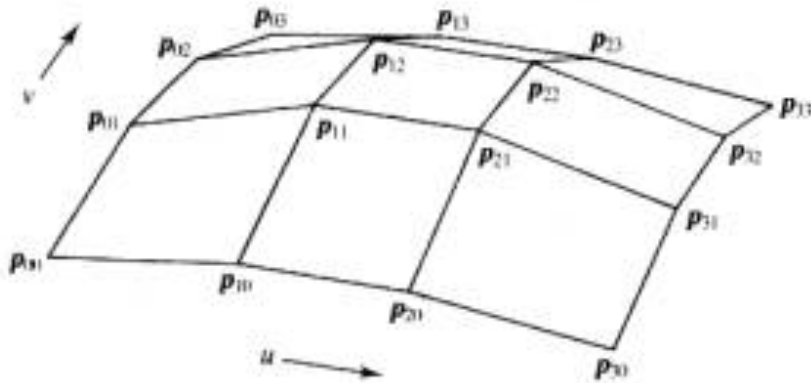
Cool: Displacement Mapping

- Not all surfaces are smooth...

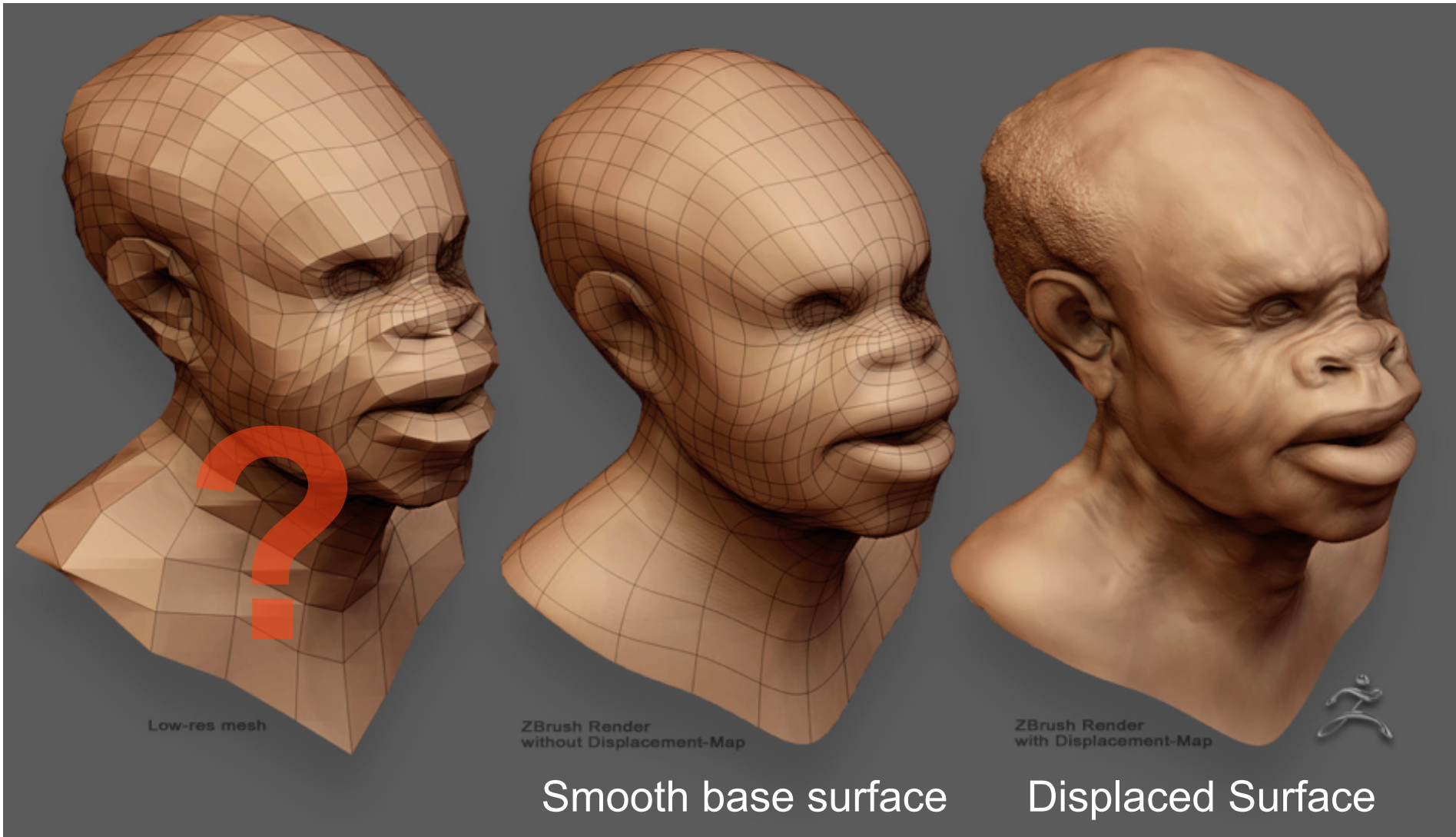


Cool: Displacement Mapping

- Not all surfaces are smooth...
- “Paint” displacements on a smooth surface
 - For example, in the direction of normal
- Tessellate smooth patch into fine grid, then add displacement $D(u,v)$ to vertices
- Heavily used in movies, more and more in games



Displacement Mapping Example



Displacement Mapping Video

- Here, input triangles are also dynamically tessellated by the GPU
- <http://www.youtube.com/watch?v=XD1C6tAqc20>

Extra: Tensor Notation

- See the slides!

Recap: Matrix Notation for Curves

- Cubic Bézier in matrix notation

point on curve
(2x1 vector)

$$P(t) = \begin{pmatrix} x(t) \\ y(t) \end{pmatrix} = \begin{pmatrix} x_1 & x_2 & x_3 & x_4 \\ y_1 & y_2 & y_3 & y_4 \end{pmatrix} \begin{pmatrix} 1 & -3 & 3 & -1 \\ 0 & 3 & -6 & 3 \\ 0 & 0 & 3 & -3 \\ 0 & 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 \\ t \\ t^2 \\ t^3 \end{pmatrix}$$

“Geometry matrix”
of control points $P_1..P_4$
(2 x 4)

“Spline matrix”
(Bernstein)

Canonical
“power basis”

Hardcore: Matrix Notation for Patches

- Not required, but convenient!

x coordinate of surface at (u,v)

$$P(u, v) = \sum_{i=1}^4 B_i(u) \left[\sum_{j=1}^4 P_{i,j} B_j(v) \right]$$

$$P^x(u, v) =$$

Column vector of basis functions (v)

$$(B_1(u), \dots, B_4(u)) \begin{pmatrix} P_{1,1}^x & \dots & P_{1,4}^x \\ \vdots & & \vdots \\ P_{4,1}^x & \dots & P_{4,4}^x \end{pmatrix} \begin{pmatrix} B_1(v) \\ \vdots \\ B_4(v) \end{pmatrix}$$

Row vector of basis functions (u)

4x4 matrix of x coordinates of the control points

Hardcore: Matrix Notation for Patches

- Curves:

$$P(t) = \mathbf{G} \mathbf{B} \mathbf{T}(t)$$

- Surfaces:

$$P^x(u, v) = \mathbf{T}(u)^T \mathbf{B}^T \mathbf{G}^x \mathbf{B} \mathbf{T}(v)$$



A separate 4x4 geometry matrix for x, y, z

- \mathbf{T} = power basis
- \mathbf{B} = spline matrix
- \mathbf{G} = geometry matrix

Super Hardcore: Tensor Notation

- You can stack the \mathbf{G}^x , \mathbf{G}^y , \mathbf{G}^z matrices into a geometry **tensor** of control points
 - I.e., $G^k_{i,j}$ = the k :th coordinate of control point $P_{i,j}$
 - A cube of numbers!

$$P^k(u, v) = \mathbf{T}^l(u) \mathbf{B}_l^i \mathbf{G}_{ij}^k \mathbf{B}_m^j \mathbf{T}^m(v)$$

- “Einstein summation convention”:
Repeated indices are summed over (here l, m, i, j)
- Definitely not required, but nice! :)
 - See http://en.wikipedia.org/wiki/Multilinear_algebra

