Supplementary material for the paper: *Generating object segmentation proposals using global and local search*.

This document contains examples of the best detections for each method (i.e. the region with the highest overlap is shown for each ground truth object). From left to right: ground truth, our method (on average 1656 regions per image), Carreira et al. (646 regions), Endres et al. (1534 regions), van de Sande et al. (1993 regions).

This sample of examples contains the first 10% of images of the test set (PASCAL VOC2012 validation set). Images annotated difficult have been excluded from this visualization. Note that the best regions for different objects may overlap, in which case the colored boundary contours that are drawn later may erase (parts of) the contours drawn first.