

EXPLICIT LINK BETWEEN PERIODIC COVARIANCE FUNCTIONS AND STATE SPACE MODELS

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- Gaussian processes and state space models
- Periodic covariance functions
- Quasi-periodic covariance functions
- Example studies



Gaussian Process Regression in 1D

The kernel approach:

 $f(t) \sim \mathcal{GP}(0, k(t, t'))$ $y_k = f(t_k) + \varepsilon_k, \quad \varepsilon_k \sim \mathcal{N}(0, \sigma_n^2),$

where the observed data is $\{(t_k, y_k), k = 1, 2, \dots, n\}.$

- Prior assumptions of the process encoded into the covariance function k(t, t').
- Can be solved in closed-form, but the naive solution scales as O(n³).



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State space approach:

$$\frac{\mathrm{d}\mathbf{f}(t)}{\mathrm{d}t} = \mathbf{F}\mathbf{f}(t) + \mathbf{L}\mathbf{w}(t)$$
$$y_k = \mathbf{H}\mathbf{f}(t_k) + \varepsilon_k, \quad \varepsilon_k \sim \mathcal{N}(\mathbf{0}, \sigma_n^2),$$

where $\mathbf{w}(t)$ is a white noise process with spectral density \mathbf{Q}_{c} .

- ► Model defined by F, L, Q_c, the stationary covariance P_∞, and the observation model H.
- Solved using Kalman filtering and Rauch–Tung–Striebel smoothing in O(n) time complexity.



Covariance and Spectral Density



Covariance function $k(\tau)$

Spectral density $S(\omega)$



GP Regression (naive solution)





GP Regression (filtering)



GP Regression (smoothing)



Periodic Covariance Functions



Start off with the squared exponential:

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The canonical periodic covariance:

$$k_{\mathrm{p}}(t,t') = \sigma^2 \exp\left(-rac{2\sin^2\left(\omega_0 rac{t-t'}{2}
ight)}{\ell^2}
ight)$$







Covariance function



State Space Formulation (1/2)

• Fourier series representation ($\tau = |t - t'|$)

$$k_{
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The model can be constructed as solutions to second-order ODEs:

$$\begin{pmatrix} \dot{x}_j(t) \\ \dot{y}_j(t) \end{pmatrix} = \begin{pmatrix} 0 & -\omega_0 \, j \\ \omega_0 \, j & 0 \end{pmatrix} \begin{pmatrix} x_j(t) \\ y_j(t) \end{pmatrix}$$



State Space Formulation (2/2)

The state space model can be given as a superposition the following kind of models:

$$\mathbf{F}_{j}^{\mathrm{p}} = \begin{pmatrix} 0 & -\omega_{0} \, j \\ \omega_{0} \, j & 0 \end{pmatrix}, \quad \mathbf{H}_{j}^{\mathrm{p}} = \begin{pmatrix} 1 & 0 \end{pmatrix}, \quad \mathbf{P}_{\infty,j}^{\mathrm{p}} = q_{j}^{2} \mathbf{I}_{2}$$

The diffusion part is zero (*i.e.* the model is deterministic).



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The spectral (variance) coefficients are

$$q_j^2 = rac{2 \, \mathsf{I}_j(\ell^{-2})}{\exp(\ell^{-2})}, ext{ for } j = 1, 2, \dots,$$

and $q_0^2 = I_0(\ell^{-2})/\exp(\ell^{-2})$, where $I_\alpha(z)$ is the modified Bessel function.



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► Taking the J first terms in the series gives an approximation, and this approximation converges uniformly to the actual covariance as J → ∞.



Approximative Covariance Function (J = 0)



Covariance function



Approximative Covariance Function (J = 1)



Covariance function



Approximative Covariance Function (J = 2)



Covariance function



Approximative Covariance Function (J = 3)



Covariance function



Quasi-Periodic Covariance Functions



Quasi-Periodic Covariance

- Allow the shape of the periodic effect to change over time.
- Take the product of a periodic covariance function k_p(t, t') with a covariance function k_q(t, t') with rather long characteristic length-scale,

$$k(t,t') = k_{\mathsf{p}}(t,t') \, k_{\mathsf{q}}(t,t'),$$

allowing the covariance to decay away from exact periodicity.





Quasi-Periodic Covariance Function



Covariance function



Quasi-Periodic Covariances in State Space Form

- State space representation of both the 'quasi' and 'periodic' part.
- The quasi-periodic state space model needs to be set up so that the feedback matrices commute (F_pF_q = F_qF_p.).
- This can be accomplished by using the special features of the Kronecker product.



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The joint model corresponding to the quasi-periodic product of the two covariance functions can then be given in a block-form:

$$\begin{array}{rcl} \mathbf{F}_{j} & = & \mathbf{F}^{\mathsf{q}} \otimes \mathbf{I}_{2} + \mathbf{I}_{q} \otimes \mathbf{F}_{j}^{\mathsf{p}}, \\ \mathbf{L}_{j} & = & \mathbf{L}^{\mathsf{q}} \otimes \mathbf{L}_{j}^{\mathsf{p}}, \\ \mathbf{Q}_{\mathsf{c},j} & = & \mathbf{Q}_{\mathsf{c}}^{\mathsf{q}} \otimes q_{j}^{\mathsf{2}} \mathbf{I}_{2}, \\ \mathbf{P}_{\infty,j} & = & \mathbf{P}_{\infty}^{\mathsf{q}} \otimes \mathbf{P}_{\infty,j}^{\mathsf{p}}, \\ \mathbf{H}_{j} & = & \mathbf{H}^{\mathsf{q}} \otimes \mathbf{H}_{j}^{\mathsf{p}}, \end{array}$$

where ' \otimes ' denotes the Kronecker product of two matrices.



Example Studies



Example: Computational Complexity





Example: Mauna Loa CO₂ Concentration

k



- CO₂ concentration observations (n = 2227, years 1958–2000 not shown in figure).
- The GP covariance function is as follows:

$$egin{aligned} \kappa(t,t') &= k_{\mathsf{SE}}(t,t') \ &+ k_{\mathsf{P}}(t,t') \, k_{
u=3/2}(t,t') \ &+ k_{
u=3/2}(t,t') \end{aligned}$$

 Converted to state space and hyperparameters optimized with respect to marginal likelihood.



Example: Daily Births in 1969–1988



- Relative number of births in the US based on daily data between 1969–1988 (n = 7305).
- The model is as follows:
 - Matern ($\nu = 7/2$) for the slow trend
 - Matern ($\nu = 3/2$) for faster variation
 - Quasi-periodic (yearly) with Matern (ν = 3/2) damping
 - Quasi-periodic (weekly) with Matern (ν = 3/2) damping
- Converted to state space and hyperparameters optimized with respect to marginal likelihood



Conclusion

- We have established the explicit connection between periodic covariance functions and state space models.
- ► This link enables the use of efficient sequential inference methods to solve periodic GP regression problems in O(n) time complexity.
- The approximation converges uniformly and a rough upper bound for the error can be given in closed-form.
- This is a 'best of both worlds' approach; it brings together the convenient model specification and hyperparametrization of GPs with the computational efficiency of state space models.





- Codes for the examples available at: http://arno.solin.fi
- The methods also implemented into the GPSTUFF toolbox for Matlab/Octave.

